

# **Vibrations on Earth-Moving Machines**

**Dan Roley  
Caterpillar  
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# Presentation Outline

- **Types of Earthmoving Machines (EMM)**
- **Vibration Reduction Systems on EMM**
- **Vibration Characteristics of EMM**
- **New ISO Vibration Standard**
- **Challenges with Vibration Reduction**
- **Future Machine Improvements**

# Earth Moving Machines

- Hauling: Trucks, Articulated Trucks, Scrapers
- Cyclic: Wheel Loaders, Dozers
- Stationary: Excavators, Backhoe Loaders



# Earth-Moving Machines

- 12 types of machines with a large size range
- Large machines that weigh over 500 tons
- Small machines that can drive through doors or gates (minimize manual handling)



# Vibration reduction systems to improve operator comfort/machine performance



## Motor Graders

1940's: Tandem rear axles were introduced on motor graders to reduce bump input by 50 %.

# Trucks – Tire/Axle Suspensions

1963: An Air/Oil Strut Suspensions were Introduced on Trucks

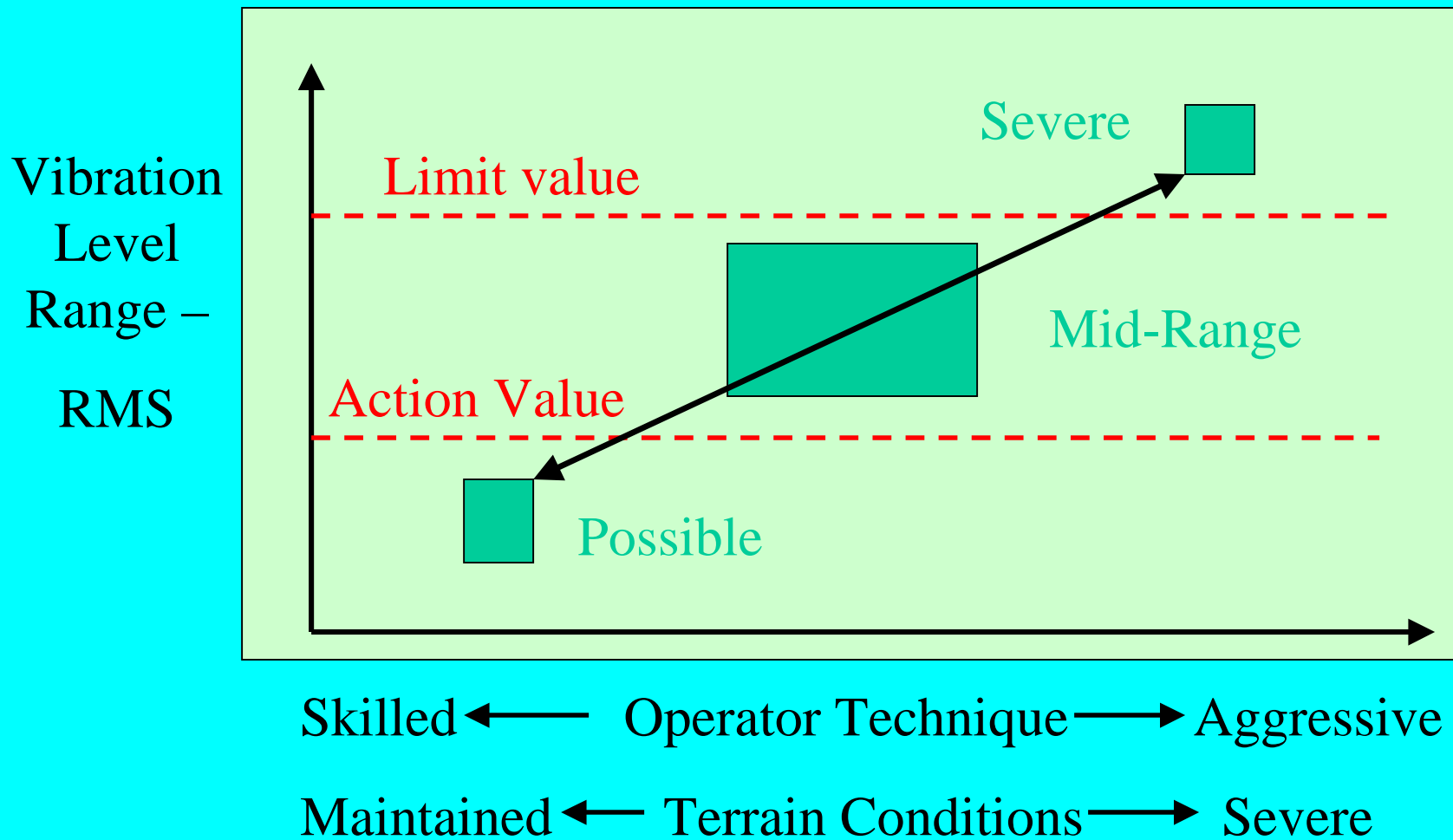




# Vibration Absorbers – Ride Control

- Loader linkage and bucket were used as dynamic absorbers starting in 1976
- Currently available on:
  - ◆ Wheel Loaders
  - ◆ Backhoe Loaders

# Vibration Characteristics of EMM



# **ISO Vibration Standard**

- **Response to EU Physical Agents Directive**
- **Define expected ranges of vibration levels**
  - **Different types of machines**
  - **Different types of applications**
  - **Vertical, fore-aft and lateral vibrations**
- **Provide guidelines for minimizing vibrations**
- **Provide guidelines for defining vibration reductions with machine improvements**

# Expected Vibration Levels

| machine kind      | typical operating condition | average frequency weighted                   |  |                                    | standard deviation (s)                 |  |  |
|-------------------|-----------------------------|--|--|------------------------------------|--|--|--|
|                   |                             | $1,4 \cdot a_{w,eqx}$<br>[m/s <sup>2</sup> ] | $1,4 \cdot a_{w,eqy}$<br>[m/s <sup>2</sup> ] | $a_{w,eqz}$<br>[m/s <sup>2</sup> ] | $1,4 \cdot s_x$<br>[m/s <sup>2</sup> ] | $1,4 \cdot s_y$<br>[m/s <sup>2</sup> ] | $1,4 \cdot s_z$<br>[m/s <sup>2</sup> ] |
| wheel loader      | load & carry motion         | 0,82   | 0,79   | 0,52                               | 0,23                                   | 0,21                                   | 0,14                                   |
| wheel loader      | mining application          | 1,19   | 0,91   | 0,81                               | 0,49                                   | 0,32                                   | 0,47                                   |
| wheel loader      | transfer movement           | 0,76   | 0,91   | 0,49                               | 0,33                                   | 0,35                                   | 0,17                                   |
| wheel loader      | V-shape motion              | 0,93   | 0,78   | 0,54                               | 0,28                                   | 0,26                                   | 0,14                                   |
| crawler excavator | excavating                  | 0,38   | 0,23   | 0,30                               | 0,19                                   | 0,12                                   | 0,17                                   |
| crawler excavator | hydraulic breaker app.      | 0,48   | 0,28   | 0,55                               | 0,25                                   | 0,14                                   | 0,28                                   |
| crawler excavator | mining application          | 0,65   | 0,42   | 0,61                               | 0,21                                   | 0,15                                   | 0,32                                   |
| crawler excavator | transfer movement           | 0,47   | 0,31   | 0,79                               | 0,19                                   | 0,20                                   | 0,23                                   |

# Vibration Challenges

- **Dependent upon operator and terrain**
- **Low Frequency/Large Displacements**
- **Machine constraints**
  - Slopes
  - Ground Contact
- **Horizontal Directions**
  - Frequency content below 2.0Hz
  - Difficult to isolate
- **Appropriate limit values**
  - Lab versus with modern seats
  - Additional 1.4 uncertainty factor
- **Other causes of back injuries**

# **Back Injury Factors/Causes**

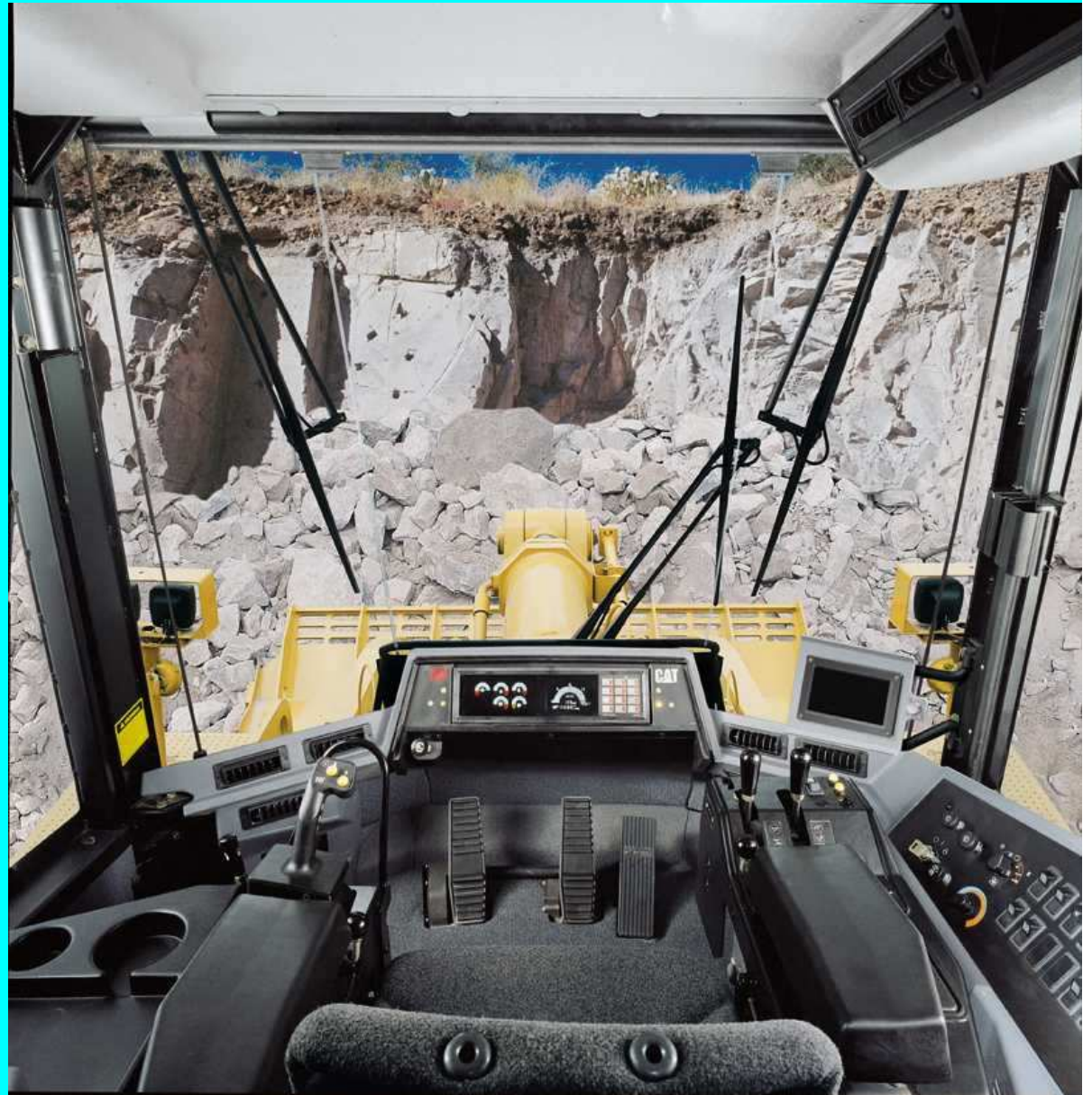
- **Lifting**
- **Long periods of sitting**
- **Twisted posture**
- **Shock loads**
  - **Jumping**
  - **Impacts**
- **Sports activities**
- **Back pain aggravated by vibrations**

# **Caterpillar Vibration Efforts**

- **Develop Comfortable Cabs**
- **Reduce Vibration Excitations**
- **Provide Information to Reduce Vibrations**

# Comfortable Operator Station

- **Seat**
  - Suspension
  - Full backrest
  - Adjustable
- **Controls**
  - Comfortable
  - Low effort
  - Seat mounted
- **Visibility**
  - Open to front
  - Mirrors for rear



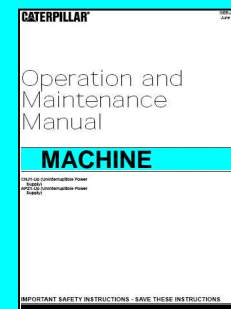
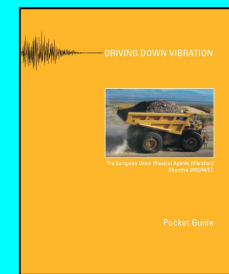
# **Future Machine Improvements**

- **Electronic Controls for Implements**
- **Electronic Power Train Controls**
- **Automated Work Cycles**
- **More Remote Control Operations**
- **Driverless Machines**

# Caterpillar's Vibration Information

Caterpillar has produced the following material to help reduce vibration levels.

- ***'Driving Down Vibration'* Brochure**
  - Media Number HEGQ3338
- ***'Driving Down Vibration'* Pocket Guidelines**
  - Media Number HEGQ3339
- **Operation & Maintenance Manual Updates**



# Summary

- 1. Many types of vibration reduction systems have been developed for earth-moving machines to reduce ride vibration levels and improve operator comfort.**
- 2. There is an opportunity to significantly reduce ride vibration levels with better training on how to operate machines and maintain the terrain conditions in the work area.**
- 3. The biggest challenge now is the horizontal directions, but the current criteria may not be realistic for seated operators on cyclic machines**
- 4. Vibration reductions will be with many small machine improvements**